

One Touch Motorised Blinds

Complete Programming

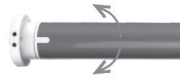
1. Delete all memory

Deleting all memory returns the motor back to factory settings. Below are two methods (A or B) that can be used.

A

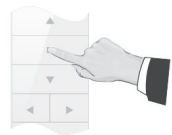


Press **PROG** four times, press for a fifth time and hold down until the motor oscillates twice

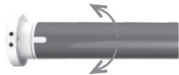


Motor memory is now erased

B



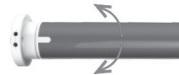
Press and hold **STOP** on the programmed remote for 5 seconds



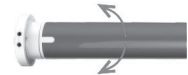
The motor oscillates once



Press and hold **SET** for 7 seconds within 10 seconds of the motor oscillating



The motor oscillates again for 1 second



The motor oscillates twice for 7 seconds, all memory is now erased

2. Pairing your handset

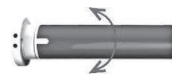
If there is no action within 10 seconds the motor will exit the programming stage automatically.



Select channel for pairing



Press the **PROG** button until the motor beeps and oscillates once



The motor is now in setting mode



Press **UP** within 10 seconds



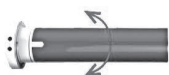
The motor oscillates again, the motor and remote are now paired

3. Change direction

If there is a need polarity can be reversed.



Press and hold **STOP** on the programmed remote for 5 seconds



The motor oscillates once



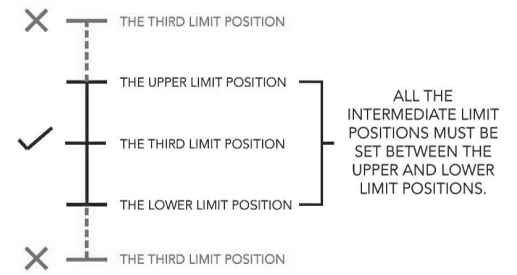
Press **DOWN** within 10 seconds



The motor oscillates again, the motor direction is now reversed

4. Limit position

- a) The first and second positions are upper/lower limit positions.
The other four are intermediate positions.
- b) After the upper/lower limit positions are set, all the intermediate positions must be set between the upper and lower limit.
- c) The upper and lower limit position can only be fine-tuned once set.
It can only be removed by deleting all the motor memory.
- d) Press the **UP** or **DOWN** button once and the motor will move to the next pre-set limit position. When the upper position has been reached the **UP** button will be unresponsive. When the lower position has been reached the **DOWN** button will become unresponsive.
- e) Press and hold the **UP** or **DOWN** button until the indicator on the programmed channel flashes twice, release, then the motor will move to the upper or lower limit position without stopping at any intermediate position.

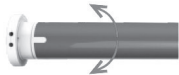


5. Setting Upper and Lower limit

Once the limits are set, the system will exit the command automatically. Both limits must be set to exit mode.



Press **SET** on the programmed remote for 1 second



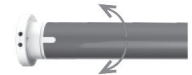
The motor oscillates once, it is now in settings mode



Press **DOWN** to the desired lower limit position then press **STOP**



Press **SET** again for 1 second



The motor oscillates once, the lower limit is now set



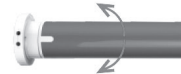
Press **UP** to the desired upper limit position then press **STOP**



Press **SET** for 1 second



Press **SET** again to confirm



The motor oscillates once, the upper limit is now set

6. Fine-tuning limit positions

Limits can be fine-tuned individually. If there is no activity for 30 seconds the system will exit the command automatically.



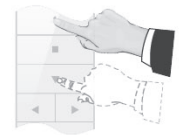
Let the motor run to the limit position



Press **SET** for 1 second



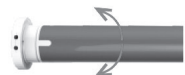
The motor oscillates once, the motor is now in setting mode



Use the **UP/DOWN** arrows to adjust to the exact position



Press **SET** again



The motor oscillates once, the fine-tuning setting is now complete

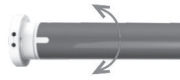
7. Setting intermediate limits



Move the blind to the desired position



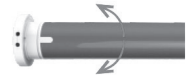
Press **SET** for 1 second



The motor oscillates once, the motor is now in setting mode



Press **SET** again



The motor oscillates once, the intermediate limit is now set

8. Deleting limit positions

The first limit set cannot be deleted separately, to remove this limit, all limits must be deleted.



Let the motor run to the limit position which needs to be deleted



Press **SET** for 7 seconds



The motor oscillates once after 1 second and then goes into setting



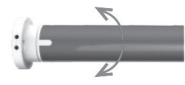
The motor oscillates once again after 7 seconds, the preset limit position is now deleted

9. Jog mode

The default movement of the motor is continuous, can be changed to jog movement or back to continuous movement for blind positioning or during fine tuning mode.



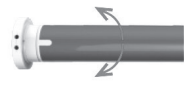
Press and hold **STOP** on the programmed remote for 5 seconds



The motor oscillates once



Press **STOP** again

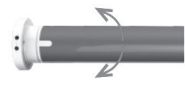


The motor oscillates again, movement mode is changed

10. Add remote



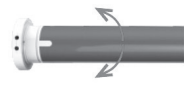
Press and hold **STOP** on the programmed remote for 5 seconds



The motor oscillates once



Press **UP** on the new remote

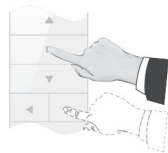


The motor oscillates again, the new remote is now added

11. Channel Locking



Press **LEFT** or **RIGHT** button and select the desired channel

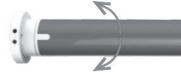


Press **STOP** and **RIGHT** buttons together for 3 seconds until remote indicator flashes twice

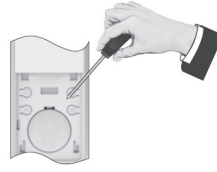
12. Delete single channel



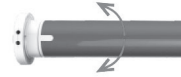
Select channel to delete, press and hold **STOP** on the programmed remote for 5 seconds



The motor oscillates once



Press **SET** for 1 second



The motor oscillates again, the selected channels memory is now deleted

13. Troubleshooting

	Issue	Cause	Solution
A	Motor does not run or runs slowly	Overload protection	Motor has been operated frequently in a short space of time or is being operated in hot conditions. Allow the motor to cool before next operation.
B	Motor does not run or runs slowly	Motor has reached its limit	Motor has reached a preset limit. Operate the blind in the opposite direction and check back for movement.
C	Motor does not run or runs slowly	Out of battery	Recharge the battery.
D	Motor does not run or runs slowly	In power off mode	Turn power on to the motor.



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